) CHAPTER SIX

) Functions and Side-Effects

<u>duction</u>

In this Chapter we extend our system to deal with functions and expressions with side effects. So far all our expressions and conditions have been terms and formulae in infinitary logic, which by their nature cannot invoke side effects; this has enabled us to keep our transformations simple. To allow side effects we introduce the new notation of "expression brackets", \lceil and \rfloor . These allow us to include statements as part of an expression, for example the folloing are valid expressions:

$$\begin{array}{c} | x := x + 1; x \\ \hline x := x + 1; x - 1 \\ x > 0 \underline{\text{then }} x \underline{\text{else}} - x \underline{\text{fi}} \end{array}$$

The first is equivalent to $\mathbf{x}+\mathbf{+}$ in C, an expression which returns the value $\mathbf{x}+\mathbf{1}$ and has the side effect of incrementing \mathbf{x} . The second is equivalent to $\mathbf{+}+\mathbf{x}$ which returns the value of \mathbf{x} before the incrementation. The third expression gives the same result as $|\mathbf{x}|$ the absolute-value function.

We define our functions in terms of procedures. A function returns a value, so within a statement a function call can be used instead of a term. So a function call can replace a term in a formula, or it can return a boolean value and replace a subformula of a formula. We can even have function calls as parameters to other functions and procedures.

<u>Defn</u>: If \mathbf{S} is a statement and \mathbf{t} a term then the "generalised expression":

 $\mathbf{S};\mathbf{t}$

is interpreted by replacing any assignment **a**:=**[S**;**t]** by **S**;**a**:=**t**. The brackets **[** and **]** are called "expression brackets".

The final component of a generalised expression can be a conditional expression of the form: **<u>if</u>** B **<u>then</u>** \mathbf{t}_1 **<u>else</u>** \mathbf{t}_2 **<u>fi</u>** where \mathbf{t}_1 abd \mathbf{t}_2 are expressions. In this case it is interpreted as he generalised expression $\lceil \underline{\mathbf{if}} \mathbf{B} \underline{\mathbf{then}} \mathbf{r} := \mathbf{t}_1 \underline{\mathbf{else}} \mathbf{r} := \mathbf{t}_2 \underline{\mathbf{fi}}; \mathbf{r} \rfloor$ where **r** is a new (local) variable. Hence the "conditional assignment": $\mathbf{a} := \underline{\mathbf{if}} \mathbf{B} \underline{\mathbf{then}} \mathbf{t}_1 \underline{\mathbf{else}} \mathbf{t}_2 \underline{\mathbf{fi}}$ may be interpreted as: **<u>beg</u> r**: **<u>if</u> B <u>then</u>** $\mathbf{r} := \mathbf{t}_1 \underline{\mathbf{else}} \mathbf{t}_2 \underline{\mathbf{fi}}$ may be interpreted as: **<u>beg</u> r**: **<u>if</u> B <u>then</u>** $\mathbf{r} := \mathbf{t}_1 \underline{\mathbf{else}} \mathbf{t}_2 \underline{\mathbf{fi}}$ may be interpreted as: **<u>beg</u> r**: **<u>if</u> B <u>then</u>** $\mathbf{a} := \mathbf{t}_1 \underline{\mathbf{else}} \mathbf{a} := \mathbf{t}_2$ **<u>fi</u>**. The expression may be used within a formula, for example: **<u>if</u>** $\lceil \mathbf{S}_1; \mathbf{t}_1 \rfloor \leq \lceil \mathbf{S}_2; \mathbf{t}_2 \rfloor \underline{\mathbf{then}} \mathbf{S}' \underline{\mathbf{fi}}$

becomes:

beg r_1, r_2 : S_1 ; $r_1:=t_1$; S_2 ; $r_2:=t_2$; if $r_1 \leq r_2$ then S' fi end.

which is equivalent to:

 $\underline{\text{beg } r: } \mathbf{S}_1; \mathbf{r}:=\mathbf{t}_1; \mathbf{S}_2; \underline{\text{if } r \leqslant t_2 \underline{\text{then } S' \underline{fi} end}}_1.$ If also \mathbf{t}_1 is invariant over \mathbf{S}_2 then both variables can be eliminated: $\mathbf{S}_1; \mathbf{S}_2; \underline{\text{if } t}_1 \leqslant \mathbf{t}_2 \underline{\text{then } S' \underline{fi}}_1.$

We may also have generalised boolean expressions: To define these we add the constants \mathbf{tt} and \mathbf{ff} which represent distinct values. (ie we include \mathbf{tt} and \mathbf{ff} in our set of constants and $\mathbf{tt}\neq\mathbf{ff}$ in our set Δ of formulae). Then if \mathbf{S} is a statement and \mathbf{Q} a formula we represent a statement of the form:

<u>if</u> [S;Q] <u>then</u> S_1 <u>else</u> S_2 <u>fi</u> by S; <u>if</u> Q <u>then</u> S_1 <u>else</u> S_2 <u>fi</u> and a loop of the form:

 $\underline{\text{while} [S;Q] \text{ do } S' \text{ od}} \text{ by the loop: } \underline{\text{do } S; \text{ if } \neg Q \text{ then exit } fi; S' \text{ od}} \text{ which may also be written as: } S; \underline{\text{while } Q \text{ do } S'; S \text{ od}}.$

If we need to assign the result of a boolean expression to a (boolean) variable then we assign one of the constants **tt** or **ff** to the variable according as the expression evaluates to true or false. For example:

 $\mathbf{b}:=[\mathbf{S};\mathbf{Q}]$ becomes: $\mathbf{S}; \mathbf{\underline{if}} \mathbf{Q} \mathbf{\underline{then}} \mathbf{b}:=\mathbf{tt} \mathbf{\underline{else}} \mathbf{b}:=\mathbf{ff} \mathbf{\underline{fi}}$

Thus a statement of the form $\underline{\mathbf{if}} \mathbf{b} \underline{\mathbf{then}} \mathbf{S}_1 \underline{\mathbf{else}} \mathbf{S}_2 \underline{\mathbf{fi}}$ where \mathbf{b} is a boolean variable becomes: { $\mathbf{b=tt} \lor \mathbf{b=ff}$ }; $\underline{\mathbf{if}} \mathbf{b=tt} \underline{\mathbf{then}} \mathbf{S}_1 \underline{\mathbf{else}} \mathbf{S}_2 \underline{\mathbf{fi}}$.

Note that expression brackets may be nested to any depth, for example:

 $\mathbf{a} := \begin{bmatrix} \mathbf{S}_1; \ \mathbf{b} := \underline{\mathbf{i}} \begin{bmatrix} \mathbf{S}_2; \mathbf{Q} \end{bmatrix} \underline{\mathbf{then}} \begin{bmatrix} \mathbf{S}_3; \ \mathbf{t}_1 \end{bmatrix} \underline{\mathbf{else}} \ \mathbf{t}_2 \ \underline{\mathbf{fi}}; \ \mathbf{b}.\mathbf{b} \end{bmatrix}$

may be represented as:

 S_1 ; S_2 ; <u>if</u> Q <u>then</u> S_3 ; b:= t_1 <u>else</u> b:= t_2 <u>fi</u>; a:=b.b

Defn: Function calls: The definitional transformation of a function call will replace the function call by a call to a procedure which assigns the value returned by the function to a variable. This variable then replaces the function call in the expression. Several calls in one expression are replaced by the same number of procedure calls and new variables. Boolean functions treated as functions which return one of the values **tt** or **ff** (representing true and false). So a boolean function call is replaced by a formula (\mathbf{b} =tt) where **b** is a new local variable. The statement in which the function call appeared is preceded by a procedure call which sets **b** to **tt** or **ff**, depending on the result of the corresponding boolean function.

For example, the function call:

 is interpreted:

 $\begin{array}{l} \underline{\operatorname{var}} \mathbf{r}_1, \mathbf{r}_2; \\ \overline{\mathbf{F}}(\mathbf{x}); \ \mathbf{r}_1 := \mathbf{r}; \ \overline{\mathbf{F}}(\mathbf{y}); \ \mathbf{r}_2 := \mathbf{r}; \\ a := \mathbf{r}_1 + \mathbf{r}_2. \ \underline{\mathrm{where}} \\ \underline{\mathrm{proc}} \ \overline{\mathbf{F}}(\mathbf{x}) \equiv \ \underline{\mathrm{if}} \ B \ \underline{\mathrm{then}} \ \mathbf{r} := t_1 \ \underline{\mathrm{else}} \ \mathbf{r} := t_2 \ \underline{\mathrm{fi}}. \end{array}$

The statement:

 $\begin{array}{l} \mathbf{a:=} \lceil \underline{while} \; B(x) \; \underline{do} \; \mathbf{x:=} F(x) \; \underline{od}; \; \mathbf{x+c} \rfloor \\ \underline{funct} \; B(x) \equiv \; \lceil \mathbf{S}; \; \mathbf{x>y} \rfloor. \\ \underline{funct} \; F(x) \equiv \; \underline{if} \; B \; \underline{then} \; t_1 \; \underline{else} \; t_2 \; \underline{fi}. \\ \hline \underline{funct} \; F(x); \; \underline{if} \; \mathbf{r=} \underline{ff} \; \underline{then} \; \underline{exit} \; \underline{fi}; \\ \mathbf{f}(x); \; \underline{x:=r} \; \underline{od}; \\ \mathbf{a:=x+c.} \; \underline{where} \\ \underline{proc} \; B(x) \equiv \; \mathbf{S}; \; \underline{if} \; x>y \; \underline{then} \; \mathbf{r:=} tt \; \underline{else} \; \mathbf{r:=} \underline{ff} \; \underline{fi}, \\ \underline{proc} \; F(x) \equiv \; \underline{if} \; B \; \underline{then} \; \mathbf{r:=} t_1 \; \underline{else} \; \mathbf{r:=} t_2 \; \underline{fi}. \end{array}$

More formally we define:

Defn: <u>Generalised expressions</u> and <u>generalised conditions</u> are defined as follows: If **S** is any statement (which may include generalised expressions and generalised conditions) and $\mathbf{E}_1, \mathbf{E}_2, \ldots$ are generalised expressions and $\mathbf{B}_1, \mathbf{B}_2, \ldots$ are generalised conditions and \mathbf{t} is a term including variables $\mathbf{x}_1, \ldots, \mathbf{x}_n$ ($\mathbf{n} \ge \mathbf{0}$) and \mathbf{Q} is a formula including free variables $\mathbf{x}_1, \ldots, \mathbf{x}_n$ ($\mathbf{n} \ge \mathbf{0}$) and $\mathbf{Q}_1, \mathbf{Q}_2, \ldots$ are formulae and $\mathbf{F}(\mathbf{x}_1, \ldots, \mathbf{x}_n)$ is a function and $\mathbf{B}(\mathbf{x}_1, \ldots, \mathbf{x}_n)$ is a Boolean function (see below) then:

(i) $\mathbf{t}[\mathbf{E}_1,...,\mathbf{E}_n/\mathbf{x}_1,...,\mathbf{x}_n]$ (ii) $\lceil \mathbf{S}; \mathbf{E}_1 \rfloor$ (iii) $\underline{\mathbf{if}} \ \mathbf{B}_1 \ \underline{\mathbf{then}} \ \mathbf{E}_1 \ \underline{\mathbf{else}} \ \mathbf{E}_2 \ \underline{\mathbf{fi}}$ (iv) $\underline{\mathbf{if}} \ \mathbf{B}_1 \ \rightarrow \mathbf{E}_1 \ \Box \ \dots \ \Box \ \mathbf{B}_n \ \rightarrow \mathbf{S}_n \ \underline{\mathbf{fi}}$ (v) $\mathbf{F}(\mathbf{E}_1,...,\mathbf{E}_n)$ are all generalised expressions and: (i) $\mathbf{Q}[\mathbf{E}_1,...,\mathbf{E}_n/\mathbf{x}_1,...,\mathbf{x}_n]$ (ii) $\mathbf{Q}[\mathbf{B}_1,...,\mathbf{B}_n/\mathbf{Q}_1,...,\mathbf{Q}_n]$ (iii) $[\mathbf{S};\mathbf{B}_1]$

(iv) $B(E_1,...,E_n)$

are all generalised conditions. (Note that setting n=0 shows that any term is also a generalised expression and any formula is also a generalised condition).

Defn: Functions and Boolean Functions:

A function $\mathbf{F}(\mathbf{x})$ is defined by: <u>funct</u> $\mathbf{F}(\mathbf{x}) \equiv \mathbf{E}$. where \mathbf{E} is a generalised expression. A Boolean function $\mathbf{B}(\mathbf{x})$ is defined by: <u>funct</u> $\mathbf{B}(\mathbf{x}) \equiv \mathbf{B}$. where \mathbf{B} is a generalised condition.

Interpretation of Generalised Expressions and Generalised Conditions

These are interpreted by "interpretation functions" IE, IC and IS where:

If \mathbf{E} is a generalised expression and \mathbf{r} a variable which does not occur in \mathbf{E} then $\mathbf{IE}(\mathbf{E},\mathbf{r})$ is a statement which sets \mathbf{r} to the value which results from evaluating the expression.

If **B** is a generalised condition and **r** a variable which does not occur in **B** then IC(B,r) is a statement which sets **r** to one of the special values **tt** or **ff** according to whether **B** evaluates to true or false.

If **S** is any statement which includes generalised expressions (in place of terms) and/or generalised conditions (in place of formulae) then IS(S) is the statement formed by replacing each assignment a:=E (where **E** is a generalised expression) by IE(E,a) and replacing each statement which uses a generalised condition by an equivalent one which uses IC to evaluate the condition. The definitions are:

where the \mathbf{x}_i are local variables which may have to be implemented using stacks.

(So for any ordinary term t: IE(t,r) = r:=t)

(ii) $IE(\mathbf{S}; \mathbf{E}_1 \mathbf{J}, \mathbf{r}) =_{DF} IS(\mathbf{S}); IE(\mathbf{E}_1, \mathbf{r})$

- (iii) $IE(\underline{if} B_1 \underline{then} E_1 \underline{else} E_2 \underline{fi}, \mathbf{r}) =_{DF} IC(B_1,\mathbf{r}); \underline{if} \mathbf{r} = tt \underline{then} IE(E_1,\mathbf{r}) \underline{else} IE(E_2,\mathbf{r}) \underline{fi}$
- (iv) IE(<u>if</u> $\mathbf{B}_1 \rightarrow \mathbf{E}_1 \square ... \square \mathbf{B}_n \rightarrow \mathbf{S}_n \underline{\mathbf{f}}_1, \mathbf{r}) =_{DF}$ <u>var</u> $\mathbf{x}_1, \mathbf{x}_2, ..., \mathbf{x}_n$ IC($\mathbf{B}_1, \mathbf{x}_1$); IC($\mathbf{B}_2, \mathbf{x}_2$); ... IC($\mathbf{B}_n, \mathbf{x}_n$); <u>if</u> $\mathbf{x}_1 = \mathbf{tt} \rightarrow \mathbf{IE}(\mathbf{E}_1, \mathbf{r}) \square ... \square \mathbf{x}_n = \mathbf{tt} \rightarrow \mathbf{IE}(\mathbf{E}_n, \mathbf{r}) \underline{\mathbf{f}}_1.$ (v) IE(F($\mathbf{E}_1, ..., \mathbf{E}_n$), \mathbf{r}) =_{DF} <u>var</u> $\mathbf{x}_1, \mathbf{x}_2, ..., \mathbf{x}_n$
 - $ext{IE}(extbf{E}_1, extbf{x}_1); ext{IE}(extbf{E}_2, extbf{x}_2); \dots ext{IE}(extbf{E}_n, extbf{x}_n); \\ extbf{F}_r(extbf{x}_1,..., extbf{x}_n).$

where \mathbf{F}_r is the "procedural equivalent" of the function \mathbf{F} which sets the global variable \mathbf{r} to the result. ie if \mathbf{F} is defined <u>funct</u> $\mathbf{F}(\mathbf{x}) \equiv \mathbf{E}$. then \mathbf{F}_r is defined as: <u>proc</u> $\mathbf{F}_r(\mathbf{x}) \equiv \mathbf{IE}(\mathbf{E},\mathbf{r})$.

Note, however, that if there are occurrences of $\mathbf{F}(\mathbf{x})$ which are interpreted with different variables then we must choose one variable \mathbf{r} for \mathbf{F}_r and for the other variables define:

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 \begin{split} \mathbf{IE}(\mathbf{F}(\mathbf{E}_1,...,\mathbf{E}_n),\,\mathbf{s}) =_{DF} \underline{\mathbf{var}} \, \mathbf{x}_1,\!\mathbf{x}_2,\!...,\!\mathbf{x}_n \\ \mathbf{IE}(\mathbf{E}_1,\!\mathbf{x}_1);\, \mathbf{IE}(\mathbf{E}_2,\!\mathbf{x}_2);\, \ldots \, \mathbf{IE}(\mathbf{E}_n,\!\mathbf{x}_n); \\ \mathbf{F}_r(\mathbf{x}_1,\!...,\!\mathbf{x}_n);\, \mathbf{s}\!:=\!\mathbf{r}. \end{split}
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IC(B,r) is defined by:
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(i) IC(Q[E<sub>1</sub>,...,E<sub>n</sub>/x<sub>1</sub>,...,x<sub>n</sub>], r) =<sub>DF</sub>

<u>var</u> x<sub>1</sub>,x<sub>2</sub>,...,x<sub>n</sub>

IE(E<sub>1</sub>,x<sub>1</sub>); IE(E<sub>2</sub>,x<sub>2</sub>); ... IE(E<sub>n</sub>,x<sub>n</sub>);

<u>if</u> Q <u>then</u> r:=tt <u>else</u> r:=ff <u>fi</u>.

(So for any ordinary formula Q: IC(Q,r) = <u>if</u> Q <u>then</u> r:=tt <u>else</u> r:=ff <u>fi</u>)

(ii) IC(Q[B<sub>1</sub>,...,B<sub>n</sub>/Q<sub>1</sub>,...,Q<sub>n</sub>], r) =<sub>DF</sub>

<u>var</u> x<sub>1</sub>,x<sub>2</sub>,...,x<sub>n</sub>

IC(B<sub>1</sub>,x<sub>1</sub>); IC(B<sub>2</sub>,x<sub>2</sub>); ... IC(B<sub>n</sub>,x<sub>n</sub>);

<u>if</u> Q <u>then</u> r:=tt <u>else</u> r:=ff <u>fi</u>.
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(iii)
$$\overline{IC}(\overline{S;B_1}, \mathbf{r}) =_{DF} \overline{IS}(S); \overline{IC}(B_1,\mathbf{r})$$

(iv) $\mathbf{IC}(\mathbf{B}(\mathbf{E}_1,...,\mathbf{E}_n/\mathbf{x}_1,...,\mathbf{x}_n), \mathbf{r}) =_{DF}$ $\underline{\mathbf{var}} \mathbf{x}_1, \mathbf{x}_2, ..., \mathbf{x}_n$ $\mathbf{IC}(\mathbf{B}_1, \mathbf{x}_1); \mathbf{IC}(\mathbf{B}_2, \mathbf{x}_2); \dots \mathbf{IC}(\mathbf{B}_n, \mathbf{x}_n);$ $\mathbf{B}_r(\mathbf{x}_1,...,\mathbf{x}_n).$

where \mathbf{B}_r is the "procedural equivalent" of the boolean function \mathbf{B} which sets the global variable \mathbf{r} to the result. ie if \mathbf{B} is defined <u>funct</u> $\mathbf{B}(\mathbf{x}) \equiv \mathbf{B}$. then \mathbf{B}_r is defined:

<u>proc</u> $B_r(x) \equiv IC(B,r)$.

IS(S) is defined by: (where **r** is a new variable) (i) $IS(S) =_{DF} S$ if \mathbf{S} contains no generalised expression or generalised condition. (ii) $IS(a:=E) =_{DF} IE(E,a)$ (ii) IS(if B then S_1 else S_2 fi) =_{DF} IE(B,r); if r=tt then IS(S₁) else IS(S₂) fi (iii) $\mathbf{IS}(\underline{\mathbf{if}} \mathbf{B}_1 \to \mathbf{S}_1 \Box \dots \Box \mathbf{B}_n \to \mathbf{S}_n \underline{\mathbf{fi}}) =_{DF}$ <u>var</u> $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n$ $IC(B_1, x_1); IC(B_2, x_2); ... IC(B_n, x_n);$ $\mathrm{\underline{if}} \ \mathbf{x}_1 = \! \mathbf{tt} \ o \ \mathbf{IS}(\mathbf{S}_1) \ \square \ ... \ \square \ \mathbf{x}_n = \! \mathbf{tt} \ o \ \mathbf{IS}(\mathbf{S}_n) \ \mathbf{\underline{fi}}.$ (iv) IS(while B do S od) $=_{DF}$ <u>do</u> IC(B,r); <u>if</u> r=ff <u>then</u> exit fi; $IS(S) \underline{od}$ (v) $\mathbf{IS}(\underline{\mathbf{do}} \ \mathbf{B}_1 \to \mathbf{S}_1 \square \dots \square \mathbf{B}_n \to \mathbf{S}_n \ \underline{\mathbf{fi}}) =_{DF}$ <u>do</u> var $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n$ $IC(B_1,x_1); IC(B_2,x_2); ... IC(B_n,x_n);$ $\underline{\mathbf{if}} \neg (\mathbf{x}_1 = \mathbf{tt} \lor \dots \lor \mathbf{x}_n = \mathbf{tt}) \underline{\mathbf{then}} \underline{\mathbf{exit}} \underline{\mathbf{fi}};$ $\overbrace{\underline{\mathrm{if}}}^{} \mathbf{x}_1 = \mathbf{tt} \rightarrow \mathbf{IS}(\mathbf{S}_1) \ \square \ \ldots \ \overbrace{\square \ \mathbf{x}_n}^{} = \overbrace{\mathbf{tt}}^{} \rightarrow \mathbf{IS}(\mathbf{S}_n) \ \underline{\mathrm{fi}}. \ \underline{\mathrm{od}}$

All other statements are defined by interpreting their components.

Transformations of Generalised Expressions

These can be derived from similar transformations of procedures and other statements, for example unfolding (replacing a function call by a copy of the body) and folding. They should be used with care because not all transformations of statements will still be valid when some of their terms are replaced by function calls. For example:

 $\begin{array}{l} \mathbf{a}:=\mathbf{t}+\mathbf{t} \text{ (where } \mathbf{t} \text{ is a term) may be replaced by } \mathbf{a}:=2.\mathbf{t} \text{ but:} \\ \mathbf{a}:=\mathbf{G}()+\mathbf{G}() \underbrace{\mathbf{where}}_{\mathbf{funct}} \mathbf{G}() \equiv \\ \underbrace{\mathbf{funct}}_{\mathbf{f}} \mathbf{G}() \equiv \\ \mathbf{0} \\ \Box \\ \mathbf{true} \rightarrow \mathbf{0} \\ \Box \\ \mathbf{true} \rightarrow \mathbf{1} \underbrace{\mathbf{fi}}_{\mathbf{fi}} \\ \text{is only } \underbrace{\mathbf{refined}}_{\mathbf{by}} \mathbf{a}:=2.\mathbf{G}() \text{ and not equivalent to it. This is because } \mathbf{a}:=\mathbf{G}()+\mathbf{G}() \text{ is equivalent to:} \end{array}$

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\begin{array}{l} \underbrace{\operatorname{var}}_{\mathbf{1},\mathbf{r}_{2}:} \mathbf{G}; \mathbf{r}_{1}:=\mathbf{r}; \mathbf{G}; \mathbf{r}_{2}:=\mathbf{r}; \mathbf{a}:=\mathbf{r}_{1}+\mathbf{r}_{2}. \ \underline{\text{where}}\\ \underline{\text{proc}} \mathbf{G} \equiv\\ \underline{\mathbf{if}} \operatorname{true} \to \mathbf{r}:=\mathbf{0}\\ \Box \ \operatorname{true} \to \mathbf{r}:=\mathbf{1} \ \underline{\mathbf{fi}}\\ \text{while } \mathbf{a}:=\mathbf{2}.\mathbf{G}() \text{ is equivalent to:}\\ \underline{\operatorname{var}} \mathbf{r}_{1}: \mathbf{G}; \mathbf{r}_{1}:=\mathbf{r}; \mathbf{a}:=\mathbf{2}.\mathbf{r}_{1}. \ \underline{\text{where}}\\ \underline{\text{proc}} \mathbf{G} \equiv\\ \underline{\mathbf{if}} \ \operatorname{true} \to \mathbf{r}:=\mathbf{0}\\ \Box \ \operatorname{true} \to \mathbf{r}:=\mathbf{1} \ \underline{\mathbf{fi}} \end{array}
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The first case is equivalent to: $\mathbf{a}:=\mathbf{a}' \cdot (\mathbf{a}'=\mathbf{0} \lor \mathbf{a}'=\mathbf{1} \lor \mathbf{a}'=\mathbf{2})$ and this may be refined by (but is not equivalent to): $\mathbf{a}:=\mathbf{a}' \cdot (\mathbf{a}'=\mathbf{0} \lor \mathbf{a}'=\mathbf{2})$, which is equivalent to the second case.

[Bauer & Wossner 80] use the notation $(\mathbf{0} \Box \mathbf{1})$ for such a "nondeterministic expression". The generalised expression $(\mathbf{E}_1 \Box \ldots \Box \mathbf{E}_n)$, which represents in our notation <u>if</u> true $\rightarrow \mathbf{E}_1 \Box \ldots \Box$ true $\rightarrow \mathbf{E}_n$ <u>fi</u>, will (nondeterministically) take one of the values $\mathbf{E}_1, \ldots, \mathbf{E}_n$.

To apply one of the transformations we have derived so far to a statement containing generalised expressions and generalised conditions first transform the statement to an ordinary one (using the interpretation functions **IS**, **IC** and **IE**), then apply the transformation (making sure that it still applies), and then apply the interpretation functions "in reverse" (if possible) to get a transformed statement containing generalised expressions and generalised conditions.

Tail-Recursion

We have the following transformation for tail-recursive procedures:

 $\begin{array}{rl} \underline{\operatorname{proc}} \ \mathbf{F}(\mathbf{x}) \equiv & \underline{\operatorname{if}} \ \mathbf{B} \ \underline{\operatorname{then}} \ \mathbf{S}_1; \ \mathbf{F}(\mathbf{g}(\mathbf{x})) \\ & \underline{\operatorname{else}} \ \mathbf{S}_2 \ \underline{\operatorname{fi}}. \\ \approx \\ & \underline{\operatorname{proc}} \ \mathbf{F}(\mathbf{x}) \equiv & \underline{\operatorname{while}} \ \mathbf{B} \ \underline{\operatorname{do}} \ \mathbf{S}_1; \ \mathbf{x}{:=} \mathbf{g}(\mathbf{x}) \ \underline{\operatorname{od}}; \ \mathbf{S}_2. \end{array}$

Note that \mathbf{S}_1 and \mathbf{S}_2 may contain further calls of $\mathbf{F}(\mathbf{x})$.

This follows from replacing the parameter by a stack: <u>proc</u> $\mathbf{F}(\mathbf{x}) \equiv \mathbf{S}:=\langle\rangle; \mathbf{F}. \underline{\mathbf{where}}$ $\mathbf{F} \equiv (\underline{\mathbf{if}} \ \mathbf{B} \ \underline{\mathbf{then}} \ \mathbf{S}_1 \ \mathbf{x}:=\mathbf{g}(\mathbf{x}); \ \mathbf{F} \ \underline{\mathbf{fi}}; \ \mathbf{S}_2)[\mathbf{S}\leftarrow\mathbf{x}; \ \mathbf{x}:=\mathbf{h}(\mathbf{x}); \ \mathbf{F}; \ \mathbf{x}\leftarrow\mathbf{S} \ / \ \mathbf{F}(\mathbf{h}(\mathbf{x}))].$

Note that we don't require **F** to preserve the value of **x** so **x** does not have to be stacked and restored for the final call F(g(x)) which has therefore been replaced by x:=g(x);F.

By the tail-recursion result of the previous Chapter this becomes: $\begin{array}{l} \underline{\text{proc}} \ \mathbf{F}(\mathbf{x}) \equiv \ \mathbf{S}{:=}\langle\rangle; \ \mathbf{F}. \ \underline{\text{where}} \\ \mathbf{F} \equiv \ (\underline{\text{while}} \ \mathbf{B} \ \underline{\text{do}} \ \mathbf{S}_1 \ \mathbf{x}{:=}\mathbf{g}(\mathbf{x}) \ \underline{\text{od}}; \ \mathbf{S}_2)[\mathbf{S}{\leftarrow}\mathbf{x}; \ \mathbf{x}{:=}\mathbf{h}(\mathbf{x}); \ \mathbf{F}; \ \mathbf{x}{\leftarrow}\mathbf{S} \ / \ \mathbf{F}(\mathbf{h}(\mathbf{x}))]. \end{array}$ Replace stack \mathbf{S} by a parameter again and copy in to get: $\begin{array}{l} \underline{\text{proc}} \ \mathbf{F}(\mathbf{x}) \equiv \ \underline{\text{while}} \ \mathbf{B} \ \underline{\text{do}} \ \mathbf{S}_1; \ \mathbf{x}{:=}\mathbf{g}(\mathbf{x}) \ \underline{\text{od}}; \ \mathbf{S}_2. \end{array}$

There is a similar result for functions:

 $\begin{array}{l} \underline{funct} \ F(x) \equiv \ \underline{if} \ B \ \underline{then} \left\lceil S_1; \ F(g(x)) \right\rfloor \\ \underline{else} \ E \ \underline{fi}. \end{array} \\ \mbox{where } E \ \mbox{is any general expression. This is equivalent to:} \\ \underline{funct} \ F(x) \equiv \left\lceil \underline{while} \ B \ \underline{do} \ S_1; \ x := g(x) \ \underline{od}; \ E \right\rfloor. \\ \mbox{The proof follows from transforming the functions to procedures.} \end{array}$

Example: Fibonacci Numbers:

The sequence of Fibonacci numbers: $0,1,1,2,3,5,8,13,21,34,...F_n,...$ is defined by: $F_1 = 0$ $F_2 = 1$ $F_{n+2} = F_{n+1} + F_n$ for n > 0

A function to evaluate \mathbf{F}_n given \mathbf{n} is: <u>funct</u> fib(\mathbf{n}) $\equiv \mathbf{F}_n$.

To transform this into a program which is not defined in terms of \mathbf{F}_n we first take out the cases $\mathbf{n=1}$ and $\mathbf{n=2}$:

 $\begin{array}{l} \underline{\mathrm{finct}} \ \mathrm{fib}(\mathbf{n}) \equiv \ \underline{\mathrm{if}} \ \mathbf{n} = 1 \ \underline{\mathrm{then}} \ \lceil \{\mathbf{n} = 1\}; \ \mathbf{F}_n \ _ \\ \underline{\mathrm{elsf}} \ \mathbf{n} = 2 \ \underline{\mathrm{then}} \ \lceil \{\mathbf{n} = 2\}; \ \mathbf{F}_n \ _ \\ \underline{\mathrm{else}} \ \lceil \{\mathbf{n} > 2\}; \ \mathbf{F}_n \ _ \underline{\mathrm{fi}}. \end{array}$

Now $\lceil \{n=1\}; F_n \rfloor \approx \lceil \{n=1\}; 0 \rfloor$ and $\lceil \{n=2\}; F_n \rfloor \approx \lceil \{n=2\}; 1 \rfloor$ from the definition of F_n , while: $\lceil \{n>2\}; F_n \rfloor \approx \lceil \{n>2\}; F_{n-1}+F_{n-2} \rfloor$

We get:

Finally we can replace $\mathbf{F}_{n-1} + \mathbf{F}_{n-2}$ by $\mathbf{fib}(\mathbf{n-1}) + \mathbf{fib}(\mathbf{n-2})$ since $\mathbf{1 \leq n-1 < n}$ and $\mathbf{1 \leq n-2 < n}$ (this follows from the theorem on recursive implementation of a specification). The result is: <u>funct</u> $\mathbf{fib}(\mathbf{n}) \equiv \underline{\mathbf{if}} \mathbf{n=1}$

 $\begin{array}{c} \underline{ then } \\ \underline{ elsf } n{=}2 \ \underline{ then } 1 \\ \underline{ else } \ fib(n{-}1){+}fib(n{-}2) \ \underline{ fi}. \end{array}$

Each call of this function with argument >2 causes two further calls, it is easy to see therefore that $\mathbf{fib}(\mathbf{n})$ results in $2^{n-1}-1$ function calls (for $\mathbf{n} \ge 1$) so the function as it stands is hopelessly inefficient. Noting however that $\mathbf{fib}(\mathbf{n})$ is defined in terms of $\mathbf{fib}(\mathbf{n}-1)$ and $\mathbf{fib}(\mathbf{n}-2)$ (for $\mathbf{n}>2$) prompts us to try the definition:

<u>funct</u> $g(n) \equiv \langle fib(n), fib(n-1) \rangle$.

for n > 1. Hence $g(2) = \langle fib(2), fib(1) \rangle = \langle 1, 0 \rangle$.

Unfolding $\mathbf{g(n+1)}$ (for $\mathbf{n>1}$) gives: $\mathbf{g(n+1)} = \langle \mathbf{fib(n+1)}, \mathbf{fib(n)} \rangle$ $= \langle \mathbf{fib(n)} + \mathbf{fib(n-1)}, \mathbf{fib(n)} \rangle$ since $\mathbf{n+1>2}$.

This is defined in terms of $\mathbf{fib}(\mathbf{n})$ and $\mathbf{fib}(\mathbf{n}-1)$ so we can write it in terms of $\mathbf{g}(\mathbf{n})$: = $\langle \mathbf{g}(\mathbf{n})[\mathbf{1}] + \mathbf{g}(\mathbf{n})[\mathbf{2}], \mathbf{g}(\mathbf{n})[\mathbf{1}] \rangle$ = $[\underline{\mathbf{beg}} \langle \mathbf{a}, \mathbf{b} \rangle := \mathbf{g}(\mathbf{n}); \langle \mathbf{a} + \mathbf{b}, \mathbf{a} \rangle \underline{\mathbf{end}}$

Hence we can prove (by the recursive implementation theorem again) that **g** is equivalent to: <u>funct</u> $\mathbf{g}(\mathbf{n}) \equiv \underline{\mathbf{if}} \mathbf{n} = 2 \underline{\mathbf{then}} \langle \mathbf{1}, \mathbf{0} \rangle$ <u>else</u> [<u>beg</u> $\langle \mathbf{a}, \mathbf{b} \rangle := \mathbf{g}(\mathbf{n} - \mathbf{1}); \langle \mathbf{a} + \mathbf{b}, \mathbf{a} \rangle \underline{\mathbf{end}} | \underline{\mathbf{fi}}.$

A procedural version of this, where $\mathbf{r}:=\mathbf{g}(\mathbf{n}) \approx \mathbf{G}(\mathbf{n})$ is:

 $\begin{array}{ll} \underline{\mathrm{proc}} \,\, G(n) \equiv \,\, \underline{\mathrm{if}} \,\, n{=}2 \,\, \underline{\mathrm{then}} \,\, r{:}{=}\langle 1{,}0\rangle \\ \underline{\mathrm{else}} \,\, \underline{\mathrm{beg}} \,\, \langle a{,}b\rangle{:}{=}g(n{-}1); \,\, r{:}{=}\langle a{+}b, \,\, a\rangle \,\, \underline{\mathrm{end}} \,\, \underline{\mathrm{fi}}. \end{array}$

Our recursion-removal techniques can now be applied to get: <u>proc</u> $G(n) \equiv n_0 := n; r := \langle 1, 0 \rangle;$

 ${\rm \underline{for}} \ {
m n}{:=}2 \ {\rm \underline{to}} \ {
m n}_0 \ {\rm \underline{step}} \ 1 \ {\rm \underline{do}} \ {
m r}{:=} \langle {
m r}[1]{+}{
m r}[2], \ {
m r}[1]
angle \ {
m \underline{od}}.$

Hence we can write **fib** in the linear form: (replacing **r** by **a** and **b** where $\mathbf{r} = \langle \mathbf{a}, \mathbf{b} \rangle$): <u>funct</u> **fib**(**n**) \equiv

$$\begin{array}{l} \underline{if} \ n=0 \ \underline{then} \ 0 \\ \underline{elsf} \ n=1 \ \underline{then} \ 1 \\ \underline{else} \ \lceil \ a:=1; \ b:=0; \\ \underline{for} \ i:=2 \ \underline{to} \ n \ \underline{step} \ 1 \ \underline{do} \\ \langle a,b \rangle:=\langle a+b,a \rangle \ \underline{od}; \\ a \ _ \underline{fi}. \end{array}$$

However, there is a still more efficient way of computing Fibonacci numbers. From the original definition it is possible to prove the equations (for $\mathbf{j} > \mathbf{2}$): $\mathbf{F}_{2j} = \mathbf{F}_j^2 + \mathbf{F}_{j+1}^2$ $\mathbf{F}_{2j+1} = (\mathbf{2} \cdot \mathbf{F}_j + \mathbf{F}_{j+1}) \cdot \mathbf{F}_{j+1}$ and $\mathbf{F}_{2j-1} = (\mathbf{2} \cdot \mathbf{F}_{j+1} - \mathbf{F}_j) \cdot \mathbf{F}_j$

Dijkstra gives proofs for these equations in [Dijkstra 79] where he challenges "proponents of program transformations" to transform the linear form of the Fibonacci numbers program into a logarithmic form which the equations suggest should be possible. We have already shown that the linear form given above is equivalent to the specification <u>funct</u> fib(n) \equiv F_n. We shall now take up Dijkstra's challenge and transform this into a logarithmic order function using transformation we have already developed.

From <u>funct</u> fib(n) \equiv F_n. we can use the proof of the equations above to transform this directly to: <u>funct</u> fib(n) \equiv $\lceil \mathbf{x} := \mathbf{F}_n \cdot (\forall \mathbf{j} \in \mathbb{N} \cdot ((\mathbf{n} = 2.\mathbf{j} \Rightarrow (\mathbf{F}_n = \mathbf{F}_j^2 + \mathbf{F}_{j+1}^2)) \land (\mathbf{n} = 2.\mathbf{j} + \mathbf{1} \Rightarrow (\mathbf{F}_n = (2.\mathbf{F}_j + \mathbf{F}_{j+1}).\mathbf{F}_{j+1})));$ $\times |.$

From this we can derive the following recursive function (using the theorem for the recursive implementation of specifications):

<u>funct</u> fib₂(j) \equiv <u>if</u> j=1 <u>then</u> 0 elsf j=2 then 1 <u>elsf</u> even(j) <u>then</u> fib₂(j/2)²+fib₂(j/2+1)² $\underline{\rm else}\;\bigl(2.{\rm fib}_2((j-1)/2) + {\rm fib}_2((j-1)/2 + 1)\bigr).{\rm fib}_2((j-1)/2 + 1)\;\underline{\rm fi}.$ Define the expression $\langle \mathbf{a} \div \mathbf{b} \rangle$ by: $\langle \mathbf{a} \div \mathbf{b} \rangle =_{DF} \langle (\mathbf{a} \text{ div } \mathbf{b}), (\mathbf{a} \text{ mod } \mathbf{b}) \rangle$. Then if we let $\langle \mathbf{q}, \mathbf{r} \rangle = \langle \mathbf{j} \div \mathbf{2} \rangle$ we have: $even(j) \iff (q=j/2 \land r=0) \text{ and } odd(j) \iff (q=(j-1)/2 \land r=1).$ So we can write \mathbf{fib}_2 as: <u>funct</u> fib₂(j) \equiv if j=1 then 0 $\underline{elsf} \ \underline{j=2} \ \underline{then} \ 1$ $\underline{\mathbf{else}}\,\lceil\langle\mathbf{q},\!\mathbf{r}\rangle\!:=\!\langle\mathbf{j}\!\div\!\mathbf{2}\rangle;$ $\underline{if} r=0$ then $fib_2(q)^2 + fib_2(q+1)^2$ $\underline{\text{else}} (2.\text{fib}_2(q) + \text{fib}_2(q+1)).\text{fib}_2(q+1) \underline{\text{fi}} \underline{\text{fi}}.$ Here we see that $\mathbf{fib}_2(\mathbf{j})$ (for $\mathbf{j} > 2$) is defined in terms of $\mathbf{fib}_2(\mathbf{q})$ and $\mathbf{fib}_2(\mathbf{q}+1)$. This suggests that we define a new function $G_2(j)$ to be (for $j \ge 2$): <u>funct</u> $G_2(j) \equiv \langle fib_2(j), fib_2(j-1) \rangle$. Taking out the cases j=2 and j=3 gives: <u>funct</u> $\mathbf{G}_2(\mathbf{j}) \equiv \underline{\mathbf{if}} \mathbf{j} = \mathbf{2} \underline{\mathbf{then}} \langle \mathbf{1}, \mathbf{0} \rangle$ <u>elsf</u> j=3 <u>then</u> (1,1) $\underline{\text{else}} [\{j > 2\}; \langle \text{fib}_2(j), \text{fib}_2(j-1) \rangle \underline{\text{fi}}.$ Unfolding the calls to \mathbf{fib}_2 gives: <u>funct</u> $G_2(j) \equiv if j=2$ then $\langle 1,0 \rangle$ <u>elsf</u> j=3 <u>then</u> (1,1)<u>else</u> $\langle \langle \mathbf{q}, \mathbf{r} \rangle := \langle \mathbf{j} \div \mathbf{2} \rangle;$ $\underline{if} r=0$ then $fib_2(q)^2 + fib_2(q+1)^2$ $\underline{\text{else}}\;(2.\text{fib}_2(q) + \text{fib}_2(q+1)).\text{fib}_2(q+1)\;\underline{\text{fi}}\,]\,,$ $\langle \mathbf{q},\mathbf{r}\rangle := \langle (\mathbf{j}-1) \div 2 \rangle;$ if r=0 then $fib_2(q)^2 + fib_2(q+1)^2$ $\underline{\text{else}} \ (2.\text{fib}_2(\mathbf{q}) + \text{fib}_2(\mathbf{q}+1)).\text{fib}_2(\mathbf{q}+1) \ \underline{\text{fi}} \) \ \underline{\text{fi}}.$

 $\begin{array}{l} \mathrm{If}\; \langle \mathbf{q}, \mathbf{r} \rangle = \langle \mathbf{j} \div \mathbf{2} \rangle \; \mathrm{and}\; \langle \mathbf{q}_1, \mathbf{r}_1 \rangle = \langle (\mathbf{j} - \mathbf{1}) \div \mathbf{2} \rangle \; \mathrm{then} \\ \mathbf{r} = \mathbf{0} \Rightarrow \left(\mathbf{q}_1 = \mathbf{q} \land \mathbf{r}_1 = \mathbf{1} \right) \; \mathrm{and}\; \mathbf{r} = \mathbf{1} \Rightarrow \left(\mathbf{q}_1 = \mathbf{q} + \mathbf{1} \land \mathbf{r}_1 = \mathbf{0} \right). \\ \mathrm{So\; we\; may\; replace\; the\; outer\; \underline{\mathbf{else}}\; \mathrm{clause\; by:} \\ \lceil \langle \mathbf{q}, \mathbf{r} \rangle := \langle \mathbf{j} \div \mathbf{2} \rangle; \; \underline{\mathbf{if}\; \mathbf{r}} = \mathbf{0} \\ \underline{\mathbf{then}}\; \langle \mathbf{fib}_2(\mathbf{q})^2 + \mathbf{fib}_2(\mathbf{q} + \mathbf{1})^2, \; \left(\mathbf{2}.\mathbf{fib}_2(\mathbf{q}) + \mathbf{fib}_2(\mathbf{q} + \mathbf{1}) \right).\mathbf{fib}_2(\mathbf{q} + \mathbf{1}) \rangle \\ \underline{\mathbf{else}}\; \langle \left(\mathbf{2}.\mathbf{fib}_2(\mathbf{q} - \mathbf{1}) + \mathbf{fib}_2(\mathbf{q}) \right).\mathbf{fib}_2(\mathbf{q}), \; \mathbf{fib}_2(\mathbf{q})^2 + \mathbf{fib}_2(\mathbf{q} + \mathbf{1})^2 \rangle \; \underline{\mathbf{fi}} \; \end{bmatrix} \end{array}$

 $fib_2(q+1) = fib(q+1) = fib(q) + fib(q-1) = fib_2(q) + fib_2(q-1)$ since fib and fib₂ are equivalent.

Now $G_2(j)$ is defined in terms of $fib_2(q)$ and $fib_2(q-1)$ (for j>3) so we can write it in terms of $G_2(q)$: <u>funct</u> $G_2(j) \equiv \underline{if} \ j=2 \ \underline{then} \ \langle 1,0 \rangle$ <u>else</u> $j=3 \ \underline{then} \ \langle 1,1 \rangle$ <u>else</u> $\lceil \langle q,r \rangle := \langle j \div 2 \rangle$; $\langle a,b \rangle := G_2(q)$; <u>if</u> $r=0 \ \underline{then} \ \langle a^2 + (a+b)^2, \ (2.a+a+b).(a+b) \rangle$ <u>else</u> $\langle (2.b+a).a, \ b^2 + a^2 \rangle \ \underline{fi} \ \underline{fi}$.

Since the argument is halved for each recursive call $G_2(j)$ only takes log(j) time.

To transform this to an iterative version we will use the standard method (a protocol stack). Convert to the procedural equivalent which sets $\langle \mathbf{a}, \mathbf{b} \rangle$ to $\mathbf{G}_2(\mathbf{j})$: **proc** $\mathbf{H}(\mathbf{j}) \equiv$

 $\begin{array}{ll} \underbrace{ \mbox{if } j=2 \ \underline{then} \ a:=1; \ b:=0 } \\ \underline{ \mbox{elsf } j=3 \ \underline{then} \ a:=1; \ b:=1 } \\ \underline{ \mbox{else} \ } \langle q,r \rangle:=\langle j \div 2 \rangle; \\ H(q); \\ \underline{ \mbox{if } r=0 \ \underline{then} \ } \langle a,b \rangle:=\langle a^2 + (a+b)^2, \ (3.a+b).(a+b) \rangle \\ \underline{ \mbox{else} \ } \langle a,b \rangle:=\langle (2.b+a).a, \ b^2 + a^2 \rangle \ \underline{fi} \ \underline{fi}. \end{array}$

Note that the only variable whose value is required after the inner call is \mathbf{r} and this has the value $\mathbf{0}$ or $\mathbf{1}$ so it can be stored on a stack which may be implemented by the binary representation of an integer \mathbf{s} . If we initialise \mathbf{s} to $\mathbf{1}$ then we can tell that the stack is empty (when $\mathbf{s}=\mathbf{1}$) which is true only for the outermost call. We get the iterative form:

```
\begin{array}{ll} \underline{proc} \ H(j) \equiv \ s{:=}1; \\ \underline{while} \ j{>}3 \ \underline{do} \ \langle j{,}r \rangle{:=}\langle j{\div}2 \rangle; \ s{:=}2.s{+}r \ \underline{od}; \\ a{:=}1; \ b{:=}j{-}2; \\ \underline{while} \ s{>}1 \ \underline{do} \\ \langle s{,}r \rangle{:=}\langle s{\div}2 \rangle; \\ \underline{if} \ r{=}0 \ \underline{then} \ \langle a{,}b \rangle{:=}\langle a^2{+}(a{+}b)^2, \ (3.a{+}b).(a{+}b) \rangle \\ \underline{else} \ \langle a{,}b \rangle{:=}\langle (2.b{+}a).a, \ b^2{+}a^2 \rangle \ \underline{fi} \ \underline{od}. \end{array}
```

The first loop sets \mathbf{j} to the most significant two bits of the binary representation of its original value (so $\mathbf{j=2}$ or $\mathbf{3}$ after the first loop). The other bits are reversed, a $\mathbf{1}$ is added in front and the result put into \mathbf{s} . The second loop reads the bits of \mathbf{s} from the least significant upwards up to but not including the initial $\mathbf{1}$.

This leads to the following iterative function for fib(n) in time O(log(n)): <u>funct</u> $fib(n) \equiv$ <u>if</u> n=1 <u>then</u> 0

```
\begin{array}{c|c} \hline \underline{else} \ \overline{\mid} \ s:=1; \\ \underline{while} \ n>3 \ \underline{do} \ \langle n,r \rangle := \langle n\div2 \rangle; \ s:=2.s+r \ \underline{od}; \\ a:=1; \ b:=n-2; \\ \underline{while} \ s>1 \ \underline{do} \\ \langle s,r \rangle := \langle s\div2 \rangle; \\ \underline{if} \ r=0 \ \underline{then} \ \langle a,b \rangle := \langle a^2 + (a+b)^2, \ (3.a+b).(a+b) \rangle \\ \underline{else} \ \langle a,b \rangle := \langle (2.b+a).a, \ b^2 + a^2 \rangle \ \underline{fl} \ \underline{od}; \\ a \ \underline{lfl}. \end{array}
```

Although this seems at first sight to be a long sequence of transformations to derive a simple program, the transformations used will occur in many other problems. With practice several of them can be applied in one step; in fact most of the transformation could be applied automatically by a suitable programming system with a little guidance required from the programmer.

Example of Function Inversion

Consider the modulo function: <u>funct</u> mod(a,b) $\equiv \iota \mathbf{x}.(\exists \mathbf{m}. \mathbf{a}=\mathbf{m}.\mathbf{b}+\mathbf{x} \land \mathbf{0} \leq \mathbf{x} < \mathbf{b}).$ where $\iota \mathbf{x}.\mathbf{Q}$ means "the unique \mathbf{x} such that \mathbf{Q} holds" ie: $\mathbf{r}:=\iota \mathbf{x}.\mathbf{Q} \approx \langle \mathbf{r} \rangle.\langle \rangle.(\mathbf{Q}[\mathbf{r}/\mathbf{x}] \land \forall \mathbf{x}.(\mathbf{Q} \Rightarrow \mathbf{x}=\mathbf{r}))$

```
From this we can derive:
funct mod(a,b) \equiv if a \ge 2.b then mod(mod(a,2.b),b)
        \underline{elsf} a \ge b \underline{then} \mod(a-b,b)
             <u>else</u> a <u>fi</u>.
    We have 0 \leq \text{mod}(a,2.b) < 2.b from the original definition, so unfolding the outer call
of mod in the first line of the second definition gives:
<u>funct</u> mod(a,b) \equiv if a \ge 2.b then if <math>mod(a,2.b) \ge b then mod(mod(a,2.b),b)
                       else mod(a,2.b) fi
        <u>elsf</u> a \ge b <u>then</u> mod(a-b,b)
             <u>else</u> a <u>fi</u>.
But \mathbf{b} \leq \mathbf{mod}(\mathbf{a}, \mathbf{2}.\mathbf{b}) < \mathbf{2}.\mathbf{b}
so 0 \leq mod(a,2.b) - b < b
so we get:
\underline{funct} \ mod(a,b) \equiv \ \underline{if} \ a \geqslant 2.b \ \underline{then} \ \underline{if} \ mod(a,2.b) \geqslant b \ \underline{then} \ mod(a,2.b) - b
                       \underline{\text{else}} \mod(a,2.b) \underline{\text{fi}}
        \underline{elsf} a \ge b \underline{then} \mod(a-b,b)
             <u>else</u> a <u>fi</u>.
From function inversion we get:
funct mod(a,b) \equiv
 var r:=a, dd:=b;
   while r \ge dd do r:=r; dd:=2.dd od;
   var z := r;
   <u>while</u> \langle \mathbf{r}, \mathbf{dd} \rangle \neq \langle \mathbf{a}, \mathbf{b} \rangle <u>do</u> dd:=dd/2;
               \mathbf{z}{:=}\,\underline{\mathbf{i}}\mathbf{f}\;\mathbf{z}{\geqslant}\mathbf{d}\mathbf{d}\;\underline{\mathbf{then}}\;\mathbf{z}{-}\mathbf{d}\mathbf{d}
                     else z fi od;
   z___.
This is simplified to:
<u>funct</u> mod(a,b) \equiv
 var r:=a, dd:=b;
   while r \ge dd \underline{do} dd := 2.dd \underline{od};
   while dd \neq b do dd = dd/2;
          \underline{if} r \geqslant dd \underline{then} r := r - dd \underline{fi} \underline{od};
   r_.
```

Here we have started from a specification of the **mod** function and used our transformations to derive an efficient program for division of numbers represented in binary notation.

Constant Propogation

 $A = \underline{while } B \underline{do} c := E_1; \ x := E_2 \underline{od}$ $B = x := f(x) \underline{where} \\ \underline{funct} f(x) \equiv \underline{if} B \underline{then} c := E_1; \ f(E_2) \\ \underline{else} x \underline{fi}.$ $C = c := E_1; \ \underline{while } B \underline{do} x := E_2 \underline{od}$ $D = c := E_1; \ x := f(x) \underline{where} \\ \underline{funct} f(x) \equiv \underline{if} B \underline{then} f(E_2) \\ \underline{else} x \underline{fi}.$ $(1) \Delta \cup \{f \text{ not in } B, E_1, E_2\} \vdash A \approx B \\ (2) \Delta \cup \{f \text{ not in } B, E_2\} \vdash C \approx D \\ (3) \Delta \cup \{x := E_1 \text{ and } c := E_2 \text{ independent, } c \text{ not in } B, \\ E_1 \text{ defined and no side-effects, } B \text{ invariant over } E_1\} \vdash A \leqslant C \\ (4) \Delta \cup \{x := E_1 \text{ and } c := E_2 \text{ independent, } f \text{ not in } B, \\ E_1 \text{ defined and no side-effects, } B \text{ invariant over } E_1\} \vdash B \leqslant D \\ (1) \text{ and } (2) \text{ follow from theorem for tail-recursion.}$

(3) follows from the induction rule for iteration. The induction step is:

while B do c:=E₁; x:=E₂ \underline{od}^{n+1}

- $\approx \underline{\text{if } B} \underline{\text{ then } c}:=E_1; x:=E_2; \underline{\text{while } B} \underline{\text{ do } c}:=E_1; x:=E_2 \underline{\text{ od}}^n \underline{\text{fi}}$
- $\leqslant \quad \underline{\text{if } B \ \underline{\text{then}}} \ c:= E_1; \ x:= E_2; \ c:= E_1; \ \underline{\text{while}} \ B \ \underline{\text{do}} \ x:= E_2 \ \underline{\text{od}} \ \underline{\text{fi}}$
- $\approx \underline{\mathbf{if}} \mathbf{B} \underline{\mathbf{then}} \mathbf{c}:=\mathbf{E}_1; \mathbf{c}:=\mathbf{E}_1; \mathbf{x}:=\mathbf{E}_2; \underline{\mathbf{while}} \mathbf{B} \underline{\mathbf{do}} \mathbf{x}:=\mathbf{E}_2 \underline{\mathbf{od}} \underline{\mathbf{fi}}$ by independence.
- $\approx \underline{\text{if } B \underline{\text{then}}} c{:=}E_1; x{:=}E_2; \underline{\text{while } B \underline{\text{do}}} x{:=}E_2 \underline{\text{od } \underline{\text{fi}}}$
- since \mathbf{E}_1 is defined and has no side effects.
- $\approx \ \mathbf{c}{:=}\mathbf{E}_1; \ \underline{\mathbf{if}} \ \mathbf{B} \ \underline{\mathbf{then}} \ \mathbf{x}{:=}\mathbf{E}_2; \ \underline{\mathbf{while}} \ \mathbf{B} \ \underline{\mathbf{do}} \ \mathbf{x}{:=}\mathbf{E}_2 \ \underline{\mathbf{od}} \ \underline{\mathbf{fi}} \ \mathrm{since} \ \mathbf{B} \ \mathrm{is invar \ over} \ \mathbf{E}_1.$
- \approx c:=E₁; <u>while</u> B <u>do</u> x:=E₂ <u>od</u> by loop rolling.

The proof of (4) is similar to that of (3) but using the induction rule for iteration.

If \mathbf{E}_1 is determinate then we get equivalence for (3) and (4).

Transforming a Cascade Recursion to Linear Recursion

Consider the following two functions:

funct
$$\mathbf{F}(\mathbf{x}) \equiv \underline{\mathbf{if}} \mathbf{P}(\mathbf{x}) \underline{\mathbf{then}} \mathbf{G}(\mathbf{x}) \underline{\mathbf{else}} \mathbf{F}(\mathbf{F}(\mathbf{H}(\mathbf{x}))) \underline{\mathbf{fi}}.$$

$$\underline{\mathrm{funct}} \ \mathrm{F}_1(\mathrm{x}) \equiv \ \underline{\mathrm{if}} \ \mathrm{P}(\mathrm{x}) \ \underline{\mathrm{then}} \ \mathrm{G}(\mathrm{x}) \ \underline{\mathrm{else}} \ \mathrm{F}_1(\mathrm{G}(\mathrm{H}(\mathrm{x}))) \ \underline{\mathrm{fi}}$$

In this section we use program transformations to aid in determining a set of constraints on \mathbf{P} , \mathbf{G} and \mathbf{H} such that \mathbf{F} and \mathbf{F}_1 are equivalent.

<u>Defn</u>: For each **x** define $\mathbf{k}(\mathbf{x}) \in \mathbb{N}$ such that: $\mathbf{P}(\mathbf{H}^{k(x)}) \land (\forall \mathbf{i}, \mathbf{0} \leq \mathbf{i} < \mathbf{k}(\mathbf{x}), \neg \mathbf{P}(\mathbf{H}^{i}(\mathbf{x})))$ where this exists (it exists for all **x** on which **F** terminates).

Theorem: Under the condition:

(1) $\forall x. P(x) \Rightarrow P(HG(x))$ we have $F(x)=F_1(x)$ for all x which satisfy $P(x) \lor P(H(x))$. **Proof:** Suppose x satisfies $P(x) \lor P(H(x))$, if P(x) holds then $F(x)=F_1(x)=G(x)$ (trivial). So suppose $\neg P(x)$ holds, then by the premise we must have P(H(x)) holds. By defin of F we have F(x) = F(F(H(x))) = F(G(H(x))) since P(H(x)). Suppose P(GH(x)) holds, then F(x) = GGH(x)By defin of F_1 we have $F_1(x) = F_1(GH(x)) = GGH(x)$ as required.

Conversely suppose $\neg \mathbf{P}(\mathbf{GH}(\mathbf{x}))$ holds, then $\mathbf{F}(\mathbf{x}) = \mathbf{F}(\mathbf{F}(\mathbf{H}(\mathbf{GH}(\mathbf{x}))))$. By (1) $\mathbf{P}(\mathbf{H}(\mathbf{x})) \Rightarrow \mathbf{P}(\mathbf{H}\mathbf{GH}(\mathbf{x}))$ so $\mathbf{F}(\mathbf{x}) = \mathbf{F}(\mathbf{G}\mathbf{H}\mathbf{GH}(\mathbf{x})) = \mathbf{F}((\mathbf{GH})^2(\mathbf{x}))$. As above, if $\mathbf{P}((\mathbf{GH})^2(\mathbf{x}))$ holds then $\mathbf{F}(\mathbf{x}) = \mathbf{G}(\mathbf{GH})^2(\mathbf{x})$, otherwise $\mathbf{F}((\mathbf{GH})^3(\mathbf{x}))$, etc.

Continuing in this way we see that $\mathbf{F}(\mathbf{x}) = \mathbf{G}(\mathbf{GH})^n(\mathbf{x})$ where **n** is the smallest such that $\mathbf{P}((\mathbf{GH})^n(\mathbf{x}))$ holds. But this is the result \mathbf{F}_1 gives since if $\neg \mathbf{P}(\mathbf{GH}(\mathbf{x}))$ then $\mathbf{F}_1(\mathbf{x}) = \mathbf{F}_1((\mathbf{GH})^2(\mathbf{x}))$ etc.

Hence $\mathbf{F}(\mathbf{x}) = \mathbf{F}_1(\mathbf{x})$ on $\{\mathbf{x} | \mathbf{P}(\mathbf{x}) \lor \mathbf{P}(\mathbf{H}(\mathbf{x}))\}$ as required.

If we assume another condition; that **G** and **H** be commutative ie: (2) $\forall \mathbf{x}. \mathbf{GH}(\mathbf{x}) = \mathbf{HG}(\mathbf{x}),$

then we can prove a more general theorem connecting ${\bf F}$ and ${\bf F}_1 {:}$

<u>Theorem</u>: Under the conditions (1) and (2) we have: $\forall \mathbf{x}. \mathbf{F}(\mathbf{x}) = \mathbf{F}_1^{k+1}(\mathbf{H}^k(\mathbf{x}))$ where $\mathbf{k} = \mathbf{k}(\mathbf{x})$ is as defined above. (We assume that **F** is defined everywhere).

Proof: By induction on **k**. If **k=0** then **P**(**x**) holds and the last theorem gives $\mathbf{F}(\mathbf{x}) = \mathbf{F}_1(\mathbf{x})$. So suppose **k>0** and the theorem holds for all **x** st **k**(**x**)<**k**. Let **x** be st **k**(**x**)=**k**. **k>0** $\Rightarrow \neg \mathbf{P}(\mathbf{x})$ holds so $\mathbf{F}(\mathbf{x}) = \mathbf{F}(\mathbf{F}(\mathbf{H}(\mathbf{x})))$ **k**(**H**(**x**))=**k**-1 <**k** (by definition of **k**(**x**)) so by induction hypothesis on **H**(**x**): $\mathbf{F}(\mathbf{H}(\mathbf{x})) = \mathbf{F}_1^{k-1+1}(\mathbf{H}^{k-1}(\mathbf{H}(\mathbf{x}))) = \mathbf{F}_1^k(\mathbf{H}^k(\mathbf{x}))$

Each application of \mathbf{F}_1 does a number of applications of \mathbf{G} and \mathbf{H} in some order with one more application of \mathbf{G} than \mathbf{H} . The order is immaterial since \mathbf{G} and \mathbf{H} commute. So we can write $\mathbf{F}_1^k(\mathbf{x}) = \mathbf{G}^{k+m} \mathbf{H}^m(\mathbf{x})$ for some $\mathbf{m} \in \mathbb{N}$, so $\mathbf{F}(\mathbf{H}(\mathbf{x})) = \mathbf{G}^{k+m} \mathbf{H}^{k+m}(\mathbf{x})$.

Also the last application of **G** in the last application of \mathbf{F}_1 must have been on something for which **P** holds, ie $\mathbf{P}(\mathbf{G}^{k+m-1}\mathbf{H}^{k+m}(\mathbf{x}))$ holds $(\mathbf{k}+\mathbf{m}-1\geq\mathbf{0} \text{ since } \mathbf{k}\geq\mathbf{1})$. So by (1) $\mathbf{P}(\mathbf{HG}(\mathbf{G}^{k+m-1}\mathbf{H}^{k+m}(\mathbf{x})))$ holds, ie $\mathbf{P}(\mathbf{H}(\mathbf{G}^{k+m}\mathbf{H}^{k+m}(\mathbf{x})))$ holds. So by applying the last theorem to $\mathbf{G}^{k+m}\mathbf{H}^{k+m}(\mathbf{x})$ we get:

$$\mathbf{F}(\mathbf{F}(\mathbf{H}(\mathbf{x}))) = \mathbf{F}(\mathbf{G}^{k+m}\mathbf{H}^{k+m}(\mathbf{x})) = \mathbf{F}_1(\mathbf{G}^{k+m}\mathbf{H}^{k+m}(\mathbf{x})) = \mathbf{F}_1(\mathbf{F}_1^k(\mathbf{H}^k(\mathbf{x}))) = \mathbf{F}_1^{k+1}(\mathbf{H}^k(\mathbf{x}))$$

Result proved by induction.

Finally, if we add the third condition:

(3)
$$\forall \mathbf{x}. \mathbf{P}(\mathbf{G}(\mathbf{x})) \Rightarrow \mathbf{P}(\mathbf{X})$$

complete equivalence is obtained:

<u>Theorem</u>: Under conditions (1), (2) and (3) we have $\forall \mathbf{x} \cdot \mathbf{F}(\mathbf{x}) = \mathbf{F}_1(\mathbf{x})$. **Proof:** We can calculate $\mathbf{k}(\mathbf{x})$ iteratively by the function: <u>funct</u> $\mathbf{k}(\mathbf{x}) \equiv \underline{\mathbf{if}} \mathbf{P}(\mathbf{x}) \underline{\mathbf{then}} \mathbf{0} \underline{\mathbf{else}} \mathbf{k}(\mathbf{H}(\mathbf{x})) + \mathbf{1} \underline{\mathbf{fi}}.$

 \mathbf{F}_1 is already in iterative form so we can write an iterative procedure to calculate $\mathbf{F}_1^{k(x)+1}(\mathbf{H}^{k(x)}(\mathbf{x}))$ which is equivalent to $\mathbf{F}(\mathbf{x})$.

First we note $\mathbf{P}(\mathbf{H}^{k(x)}(\mathbf{x}))$ always holds and so $\mathbf{F}_1(\mathbf{H}^{k(x)}(\mathbf{x})) = \mathbf{G}(\mathbf{H}^{k(x)}(\mathbf{x}))$. So $\mathbf{F}(\mathbf{x}) = \mathbf{F}_1^{k(x)+1}(\mathbf{H}^{k(x)}(\mathbf{x})) = \mathbf{F}_1^{k(x)}(\mathbf{G}\mathbf{H}^{k(x)}(\mathbf{x}))$ The following routine sets \mathbf{x} to $\mathbf{F}_1(\mathbf{x}_0)$ where \mathbf{x}_0 is the initial value of \mathbf{x} : $\mathbf{F}_1 \equiv \underline{\text{while}} \neg \mathbf{P}(\mathbf{x}) \underline{\text{do}} \mathbf{x} := \mathbf{GH}(\mathbf{x}) \underline{\text{od}}; \mathbf{x} := \mathbf{G}(\mathbf{x})$ We can use this to give an iterative routine for \mathbf{F} : $\mathbf{F}\kappa\kappa \equiv \kappa\kappa\mathbf{k:=0};$ while $\neg P(\mathbf{x})$ do $\mathbf{x}:=\mathbf{H}(\mathbf{x})$; $\mathbf{k}:=\mathbf{k}+1$ od; $\{\mathbf{k}=\mathbf{k}(\mathbf{x}_0) \land \mathbf{x}=\mathbf{H}^k(\mathbf{x}_0)\}$; $\mathbf{x}:=\mathbf{G}(\mathbf{x}); \{\mathbf{k}=\mathbf{k}(\mathbf{x}_0) \land \mathbf{x}=\mathbf{G}\mathbf{H}^k(\mathbf{x}_0)\};$ while $k \neq 0$ do F_1 ; k:=k-1 od. where we have added some assertions to make it clearer. Copy \mathbf{F}_1 into \mathbf{F} to get: $\mathbf{F} \equiv \kappa \kappa \kappa \kappa \mathbf{k} := \mathbf{0};$ <u>while</u> $\neg P(x)$ <u>do</u> x := H(x); k := k+1 <u>od</u>; x := G(x);while k≠0 do <u>while</u> $\neg P(x)$ <u>do</u> x := GH(x) <u>od</u>; x:=G(x); k:=k-1 od. Writing the last two statements of \mathbf{F} in the form of unguarded loops and <u>exits</u> gives: $\mathbf{F}_2 \equiv \kappa \kappa \kappa \kappa \mathbf{x} := \mathbf{G}(\mathbf{x});$ <u>do</u> if k=0 then exit fi; $\underline{do \ if} P(x) \underline{then} \underline{exit} \underline{fi};$ $x := GH(x) \underline{od};$ x:=G(x); k:=k-1 od.we can exchange the last two assignments since they are independent: $\mathbf{F}_2 \equiv \kappa \kappa \kappa \kappa \mathbf{x} := \mathbf{G}(\mathbf{x});$ <u>do</u> if k=0 then exit fi; $\underline{do \ if} P(x) \underline{then} \underline{exit} \underline{fi};$ $x := GH(x) \underline{od};$ k:=k-1; x:=G(x) od.

this is of the form: **a**; **do t**; **b**; **a od** where **a** and **b** are <u>proper sequences</u> of statements (ie they contain no <u>exit(n)</u>s within less than **n** nested loops). So we can apply loop inversion to this to get <u>do</u> **a**; **t**; **b** <u>od</u> ie:

$$\begin{split} \mathbf{F}_2 &\equiv \kappa \kappa \kappa \kappa \underline{\mathbf{do}} \ \mathbf{x}{:=} \mathbf{G}(\mathbf{x}) \\ \underline{\mathbf{if}} \ \mathbf{k}{=} \mathbf{0} \ \underline{\mathbf{then}} \ \underline{\mathbf{exit}} \ \underline{\mathbf{fi}}; \\ \underline{\mathbf{do}} \ \underline{\mathbf{if}} \ \mathbf{P}(\mathbf{x}) \ \underline{\mathbf{then}} \ \underline{\mathbf{exit}} \ \underline{\mathbf{fi}}; \\ \mathbf{x}{:=} \mathbf{GH}(\mathbf{x}) \ \underline{\mathbf{od}}; \\ \mathbf{k}{:=} \mathbf{k}{-} \mathbf{1} \ \underline{\mathbf{od}}. \end{split}$$

Since the assignment $\mathbf{x}:=\mathbf{G}(\mathbf{x})$ doesn't change the value of \mathbf{k} we can push it inside the <u>if</u> statement)o get: if k=0 then x:=G(x); exit else x:=G(x) fi; and detach the else part (since the if part causes an \underline{exit}) to get $\underline{if} k=0$ then x:=G(x); $\underline{exit} \underline{fi}$; x:=G(x); Now use the inverse of absorption on $\mathbf{x}:=\mathbf{G}(\mathbf{x})$ to take it outside the loop: $\mathbf{F}_2 \equiv \underline{\mathbf{do}} \, \underline{\mathbf{if}} \, \mathbf{k} = \mathbf{0} \, \underline{\mathbf{then}} \, \underline{\mathbf{exit}} \, \underline{\mathbf{fi}};$ x := G(x); $\underline{do \ if} P(x) \underline{then \ exit \ fi};$ $x := GH(x) \underline{od};$ k:=k-1 od;x := G(x).Re-writing this using <u>while</u> loops gives: $\mathbf{F}_2 \equiv \mathbf{while} \ \mathbf{k} \neq \mathbf{0} \ \mathbf{do}$ x := G(x);<u>while</u> $\neg P(x)$ <u>do</u> $x := GH(x) \underline{od};$ $k := k-1 \underline{od};$ x := G(x).and finally copy this back into \mathbf{F} to get: $\mathbf{F} \equiv \mathbf{k} := \mathbf{0};$ <u>while</u> $\neg P(x)$ <u>do</u> x := H(x); k := k+1 <u>od</u>; <u>while</u> $k \neq 0$ <u>do</u> x := G(x);<u>while</u> $\neg P(x)$ <u>do</u> $x := GH(x) \underline{od};$ $k := k-1 \underline{od};$ x := G(x).

 $\mathbf{F}_1 \equiv \underline{\text{while}} \neg \mathbf{P}(\mathbf{x}) \underline{\text{do}} \mathbf{x} := \mathbf{GH}(\mathbf{x}) \underline{\text{od}}; \mathbf{x} := \mathbf{G}(\mathbf{x}).$

To show that the final versions of \mathbf{F} and \mathbf{F}_1 are equivalent we will introduce a change in the data representation: for a fixed \mathbf{x}_0 we represent $\mathbf{G}^i \mathbf{H}^j(\mathbf{x}_0)$ by the ordered pair of natural numbers (i,j),

thus our representation function is: $\Psi(\mathbf{G}^{i}\mathbf{H}^{j}(\mathbf{x}_{0})) = (\mathbf{i},\mathbf{j}) \ \mathbf{i},\mathbf{j} \in \mathbb{N}$. $\mathbf{P}(\mathbf{x}) \text{ becomes } \mathbf{P}_{1}(\mathbf{i},\mathbf{j}) \text{ where } \mathbf{P}_{1}(\mathbf{i},\mathbf{j}) \iff \mathbf{P}(\mathbf{G}^{i}\mathbf{H}^{j}(\mathbf{x}_{0}))$

 $\mathbf{x}:=\mathbf{H}(\mathbf{x})$ becomes $\mathbf{j}:=\mathbf{j}+1$ and $\mathbf{x}:=\mathbf{G}(\mathbf{x})$ becomes $\mathbf{i}:=\mathbf{i}+1$.

This representation is well-defined because **G** and **H** commute, so the result of any sequence of **G**'s and **H**'s applied to \mathbf{x}_0 can be expressed in the form $\mathbf{G}^i \mathbf{H}^j(\mathbf{x}_0)$ for some pair $\langle \mathbf{i}, \mathbf{j} \rangle$. Under this representation **F** and **F**₁ for a given \mathbf{x}_0 become **K**; $\mathbf{j}:=\mathbf{j}+\mathbf{1}$ and **K**₁; $\mathbf{j}:=\mathbf{j}+\mathbf{1}$ where

 $\begin{array}{l} {\bf K}_{{\cal K}{\cal K}{\cal K}} \ \equiv \ i{:=}0; \ j{:=}0; \ k{:=}0; \\ \underline{{\rm while}} \ \neg {\bf P}_1(i,j) \ \underline{{\rm do}} \ i{:=}i{+}1; \ k{:=}k{+}1 \ \underline{{\rm od}}; \ \{k{=}k(x_0) \ \land \ i{=}k\}; \\ \underline{{\rm while}} \ k{\neq}0 \ \underline{{\rm do}} \\ j{:=}j{+}1; \\ \underline{{\rm while}} \ \neg {\bf P}_1(i,j) \ \underline{{\rm do}} \ i{:=}i{+}1; \ j{:=}j{+}1 \ \underline{{\rm od}}; \\ k{:=}k{+}1 \ \underline{{\rm od}}. \\ {\bf K}_1 \ \equiv \ i{:=}0; \ j{:=}0; \ \underline{{\rm while}} \ \neg {\bf P}_1(i,j) \ \underline{{\rm do}} \ i{:=}i{+}1; \ j{:=}j{+}1 \ \underline{{\rm od}}. \end{array}$

where we have left out the final $\mathbf{j}:=\mathbf{j}+\mathbf{1}$ in both routines to simplify the exposition. If we can show that the final values of \mathbf{i} and \mathbf{j} after \mathbf{K} are the same as after \mathbf{K}_1 then we have proved the equivalence of \mathbf{F} and \mathbf{F}_1 for all initial values \mathbf{x}_0 .

This can be proved using the following assertions:

(1) **K** and **K**₁ both finish on the diagonal of the (i,j) plane, ie i=j finally. **Proof:** In **K**₁ the assertion i=j is set up by the first assignments and remains invariant over the loop. In **K** the assertion i-k-j=0 is set up by the first assignments and preserved in the first loop. In the inner loop the value of i-j-k is preserved so the assertion i-k-j=0 is satisfied after each outer loop. On exit we have k=0 hence i=j.

(2) For $\mathbf{K}_1 \mathbf{P}_1(\mathbf{i}, \mathbf{i})$ holds on exit (since $\mathbf{i}=\mathbf{j}$) and $\forall \mathbf{l}, \mathbf{0} \leq \mathbf{l} < \mathbf{i}$. $\neg \mathbf{P}_1(\mathbf{l}, \mathbf{l})$ holds. **Proof:** \mathbf{i} and \mathbf{j} are only incremented when $\neg \mathbf{P}_1(\mathbf{i}, \mathbf{j})$ holds. Also $\forall \mathbf{l}, \mathbf{i} \leq \mathbf{l} \mathbf{P}_1(\mathbf{l}, \mathbf{l})$ holds since $\mathbf{P}_1(\mathbf{l}, \mathbf{l}) \Rightarrow \mathbf{P}_1(\mathbf{l}+\mathbf{1}, \mathbf{l}+\mathbf{1})$ by condition (1). So \mathbf{K}_1 finishes on the first point on the diagonal such that \mathbf{P}_1 holds.

(3) For K $((i>0 \land j>0) \Rightarrow \neg P_1(i-1,j-1))$ is an invariant.

Proof: It trivially holds in the first loop since j=0. In the outer loop, after the execution of j:=j+1 we have:

Case(i): j=1: i=k>0 so $\neg P_1(i-1,0)$ holds (by defined for k) so $\neg P_1(i-1,j-1)$ holds. Case(ii): j>1: i=k>0 so $\neg P_1(i-1,j-2)$ holds, since the invariant holds before the assignment, so by condition (3) $P_1(i-1,j-1+1)=P_1(i-1,j-1)$ so $\neg P_1(i-1,j-1)$ holds. In the inner loop the guard gives $\neg P_1(i,j)$ so after the assignments $\neg P_1(i-1,j-1)$ holds. Let i_1 be the value of i after K_1 . By (1) and (3) we have after $K: i=j \land P_1(i,i) \land (i>0 \Rightarrow \neg P_1(i-1,i-1))$ By (2): $P_1(i,i) \Rightarrow i \ge i_1 \ge 0$ while $(i>0 \Rightarrow \neg P_1(i-1,i-1)) \Rightarrow i-1 < i_1$. Hence $i=i_1$ and K and K_1 are equivalent.

Hence \mathbf{F} and \mathbf{F}_1 are equivalent as required.

Example:

McCarthy's "91-Function" (cf [McCarthy 60]) is defined: <u>funct</u> $\mathbf{F}(\mathbf{x}) \equiv$ <u>if</u> \mathbf{x} >100 <u>then</u> \mathbf{x} -10 <u>else</u> $\mathbf{F}(\mathbf{F}(\mathbf{x}+\mathbf{11}))$ <u>fi</u>.

Here $P(x) \iff x > 100$, G(x)=x-10 and H(x)=x+11. So for all x: GH(x)=HG(x)=x+1. The three conditions hold since:

(1): $\forall \mathbf{x}. \mathbf{x} > 100 \Rightarrow \mathbf{x} + 1 > 100$ (2): $\forall \mathbf{x}. \mathbf{GH}(\mathbf{x}) = \mathbf{HG}(\mathbf{x}) = \mathbf{x} + 1$

(3): $\forall \mathbf{x}. \mathbf{x} - \mathbf{10} > \mathbf{100} \Rightarrow \mathbf{x} > \mathbf{100}.$

So by applying the theorem \mathbf{F} is equivalent to \mathbf{F}_1 where:

<u>funct</u> $\mathbf{F}_1(\mathbf{x}) \equiv$

 $\mathrm{\underline{if}} \ \mathrm{x}{>}100 \ \mathrm{\underline{then}} \ \mathrm{x}{-}10 \ \mathrm{\underline{else}} \ \mathrm{F}_1(\mathrm{x}{+}1) \ \mathrm{\underline{fi}}.$

This is equivalent to the tail-recursive procedure:

<u>proc</u> $\mathbf{F}_1 \equiv$

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\underline{\text{if}} \text{ x>100 } \underline{\text{then}} \text{ r:=x-10 } \underline{\text{else}} \text{ x:=x+1; } \mathbf{F}_1 \underline{\text{fi}}
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If $\mathbf{x} \leq \mathbf{101}$ initially then this repeatedly increments \mathbf{x} until it is greater than $\mathbf{100}$ and the subtracts $\mathbf{10}$. Hence if $\mathbf{x} \leq \mathbf{101}$ initially this procedure is equivalent to: **proc** $\mathbf{F}_2 \equiv \mathbf{r}:=\mathbf{91}$. (From which we get the name of the function!).

A rigorous proof of this uses the induction rule for recursion. We have: ${x \leq 101}$; if x>100 then r:=x-10 else r:=91 fi

 $\approx \{x \leq 101\}; \underline{\text{if}} x > 100 \underline{\text{then}} \{x=101\}; r:=x-10 \underline{\text{else}} r:=91 \underline{\text{fi}}$

 $\approx \ \{x \leqslant 101\}; \text{ } \underline{\text{if }} x > 100 \text{ } \underline{\text{then }} r := 91 \text{ } \underline{\text{else }} r := 91 \text{ } \underline{\text{fi}}$

 $\approx \ \{x{\leqslant}101\};$ r:=91.

 $\begin{array}{l} {\rm If \ we \ let \ t \ be \ the \ term: \ 101-x \ then \ we \ have: } \\ \{x{\leqslant}101\}; \ \underline{if} \ x{>}100 \ \underline{then} \ r{:=}x{-}10 \ \underline{else} \ x{:=}x{+}1; \ F_1 \ \underline{fi} \\ \approx \ \{x{\leqslant}101\}; \ t_0{:=}101{-}x; \ \{t_0 \geqslant 0\}; \\ \underline{if} \ x{>}100 \ \underline{then} \ r{:=}x{-}10 \ \underline{else} \ x{:=}x{+}1; \ \{101{-}x{<}t_0\}; \ F_1 \ \underline{fi} \end{array}$

Hence by the induction rule for recursion, for $\mathbf{x} \leqslant 101$ initially, \mathbf{F}_1 is equivalent to:

proc $F_2 \equiv r:=91$. and hence F is equivalent to funct $F_3(x) \equiv 91$.